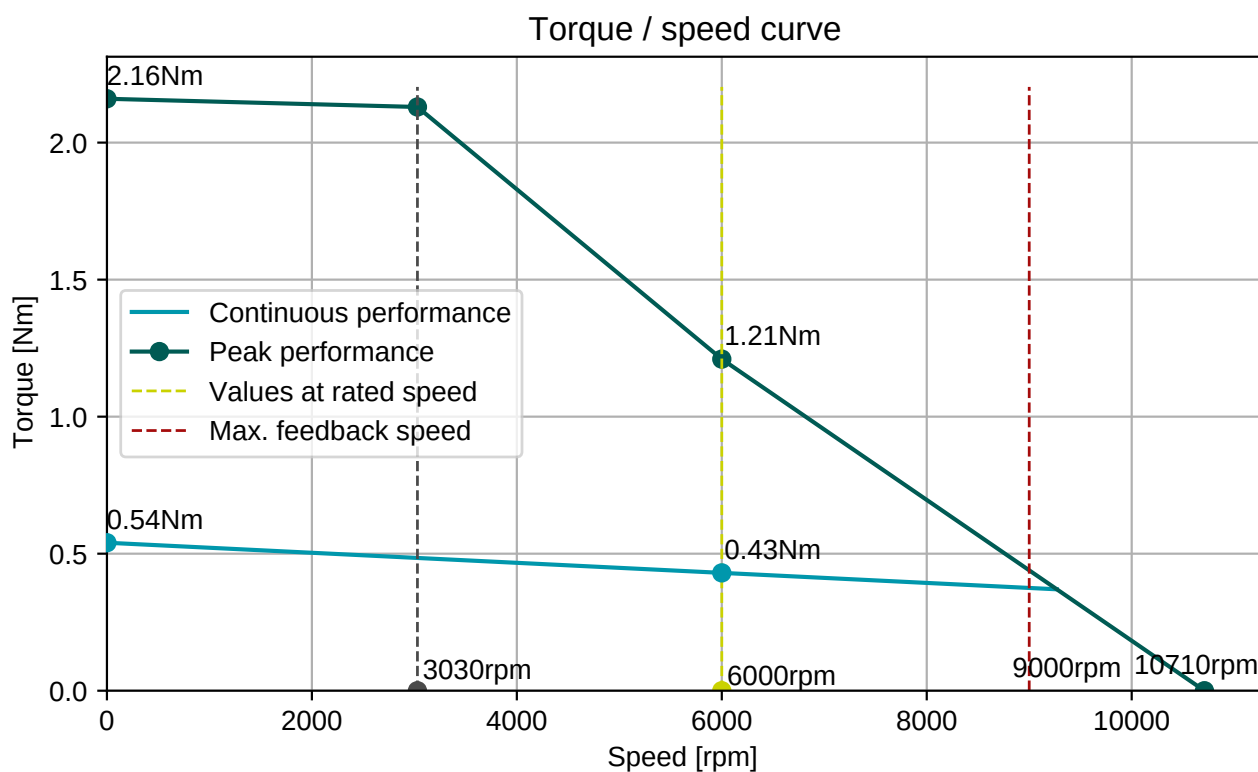


Engineering data (WIN 1659)		Mechanical data (setting 48)	
DC bus voltage	560 V DC	Max mechanical speed	12000 rpm
Nominal AC voltage	380 V AC (rms)	Mech. time constant	1.49 ms
Rated voltage	262 V AC (rms)	Thermal time constant	12 min
Rated power	270 W	Rotor inertia	0.07 kgcm ²
Rated speed	6000 rpm	Protection	IP64
Rated torque	0.43 Nm	Color	RAL 9005
Rated current	0.82 A (rms)	Cooling	Convection
Peak torque	2.16 Nm	Motor-only mass	0.9 kg
Peak current	4.3 A (rms)	Max. axial force 20kh	35 N
Stall torque	0.54 Nm	Max. radial force 20kh	186 N*
Stall current	0.93 A (rms)	Max. axial force 100kh	21 N
No load speed	10710 rpm	Max. radial force 100kh	109 N*
EMF constant ±10%	35 V AC (rms) / 1000rpm	* Defined for point of action at ½ output shaft length	
Theoretical torque constant ±10%	0.579 Nm / A (rms)		
Torque constant ±10% @ rated load	0.524 Nm / A (rms)	Sensors Temperature PT1000 {PT1000} Feedback EKM36 (HDSL) multi-turn, 17 + 12 bits	
Number of poles	6		
Electrical time constant	1.25 ms		
Winding terminal resistance	41.096 Ω		
Rotary field terminal inductance	51.2 mH		
Customs info			
HS Code	85015100		



Cable DSL4x1 (2x0,25) , D=10,3±0,4mm

Connector 1 (306)	
1	U
2	V
3	W
PE	PE
5	Brake+
6	Brake-
brown	+Us/DSL+
white	GND/DSL-

Numbers printed on the cables

