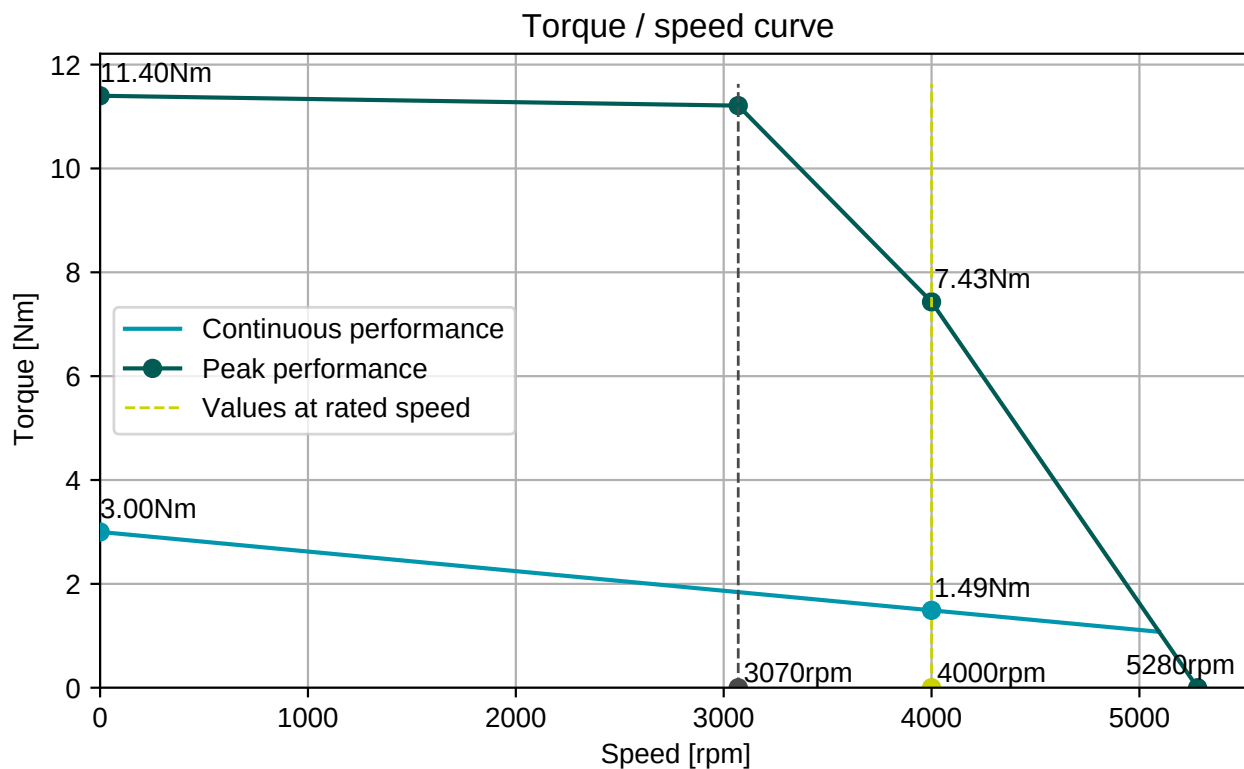
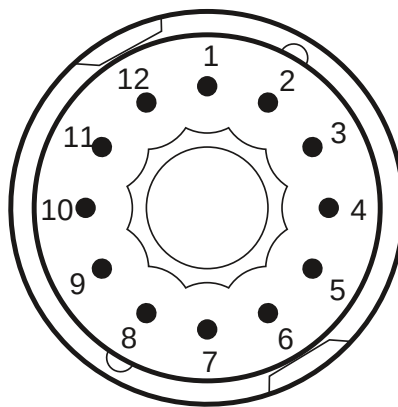
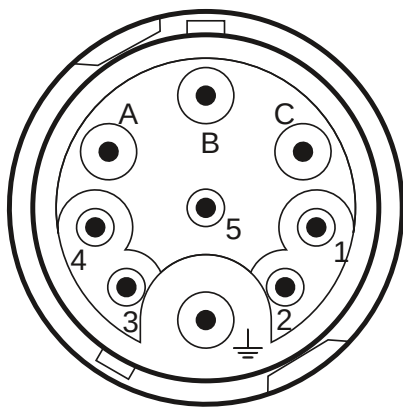


Engineering data (WIN 1620)		Mechanical data (setting 49)	
DC bus voltage	320 V DC	Max mechanical speed	12000 rpm
Nominal AC voltage	220 V AC (rms)	Mech. time constant	1.09 ms
Rated voltage	162 V AC (rms)	Thermal time constant	40 min
Rated power	624 W	Rotor inertia	1.2 kgcm ²
Rated speed	4000 rpm	Protection	IP64
Rated torque	1.49 Nm	Color	RAL 9005
Rated current	2.68 A (rms)	Cooling	Convection
Peak torque	11.4 Nm	Motor-only mass	3.3 kg
Peak current	18.8 A (rms)	Max. axial force 20kh	62 N
Stall torque	3 Nm	Max. radial force 20kh	328 N*
Stall current	4.37 A (rms)	Max. axial force 100kh	36 N
No load speed	5280 rpm	Max. radial force 100kh	192 N*
EMF constant ±10%	41.5 V AC (rms) / 1000rpm	* Defined for point of action at ½ output shaft length	
Theoretical torque constant ±10%	0.686 Nm / A (rms)		
Torque constant ±10% @ rated load	0.556 Nm / A (rms)		
Number of poles	10	Sensors	
Electrical time constant	1.62 ms	Temperature	PT1000 {PT1000}
Winding terminal resistance	2.479 Ω	Feedback	SKM36 (Hiperface) multi-turn, 128 sin/cos+12bits
Rotary field terminal inductance	4.02 mH	Brake	
Customs info		Braking torque	4.50 Nm
HS Code	85015100	Voltage	24 V DC
		Power @20°C	12.0 W
		Current @20°C	0.50 A
		Inertia	0.20 kgcm ²
		Mass	0.47 kg



EGA101N00000001000
 2x M15, 9 and 12 poles rotary



Connector 1 (226)

A	U
B	V
C	W
PE	PE
1	Brake+
2	Brake-

Connector 2 (208)

1	Us
2	GND
3	+ COS
4	REFCOS
5	REFSIN
6	+ SIN
7	Therm+
8	Therm-
9	Data +
10	Data -

