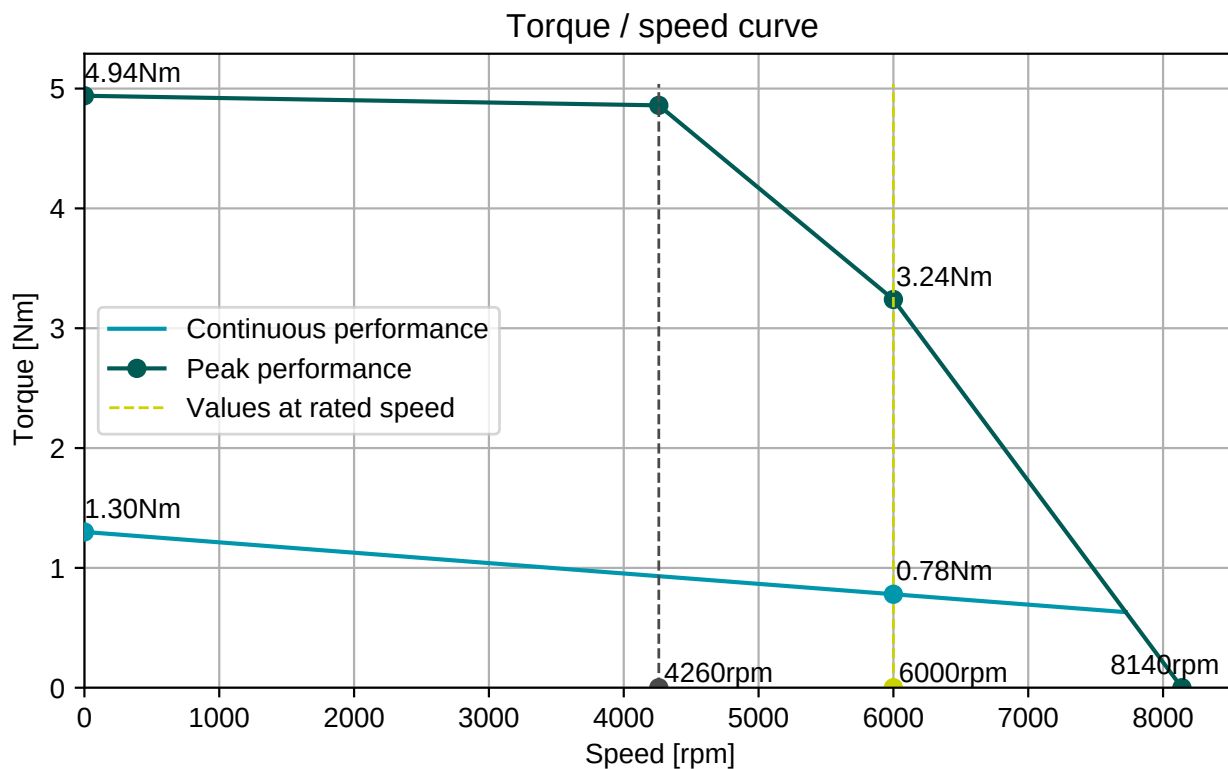
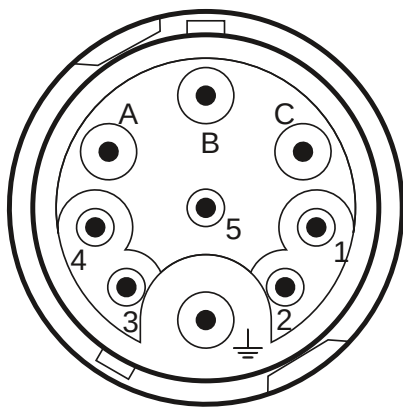


Engineering data (WIN 1270)		Mechanical data (setting 49)	
DC bus voltage	560 V DC	Max mechanical speed	12000 rpm
Nominal AC voltage	380 V AC (rms)	Mech. time constant	1.53 ms
Rated voltage	276 V AC (rms)	Thermal time constant	24 min
Rated power	490 W	Rotor inertia	0.5 kgcm ²
Rated speed	6000 rpm	Protection	IP64
Rated torque	0.78 Nm	Color	RAL 9005
Rated current	1.27 A (rms)	Cooling	Convection
Peak torque	4.94 Nm	Motor-only mass	2.1 kg
Peak current	8.33 A (rms)	Max. axial force 20kh	45 N
Stall torque	1.3 Nm	Max. radial force 20kh	237 N*
Stall current	1.77 A (rms)	Max. axial force 100kh	26 N
No load speed	8140 rpm	Max. radial force 100kh	139 N*
EMF constant ±10%	44.5 V AC (rms) / 1000rpm	* Defined for point of action at ½ output shaft length	
Theoretical torque constant ±10%	0.734 Nm / A (rms)	Sensors	
Torque constant ±10% @ rated load	0.614 Nm / A (rms)	Temperature	PT1000 {PT1000}
Number of poles	10	Feedback	SKM36 (Hiperface) multi-turn, 128 sin/cos+12bits
Electrical time constant	1.44 ms	Brake	
Winding terminal resistance	9.598 Ω	Braking torque	4.50 Nm
Rotary field terminal inductance	13.8 mH	Voltage	24 V DC
Customs info		Power @20°C	12.0 W
HS Code	85015100	Current @20°C	0.50 A
		Inertia	0.20 kgcm ²
		Mass	0.47 kg

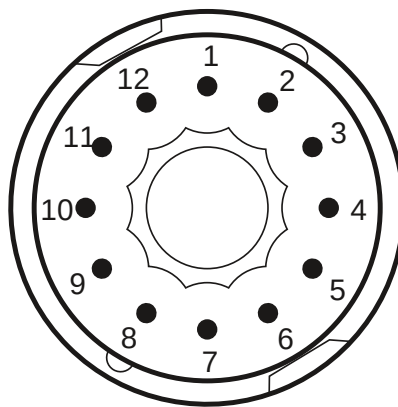


EGA101N00000001000
 2x M15, 9 and 12 poles rotary



Connector 1 (226)

A	U
B	V
C	W
PE	PE
1	Brake+
2	Brake-



Connector 2 (208)

1	Us
2	GND
3	+ COS
4	REFCOS
5	REFSIN
6	+ SIN
7	Therm+
8	Therm-
9	Data +
10	Data -

