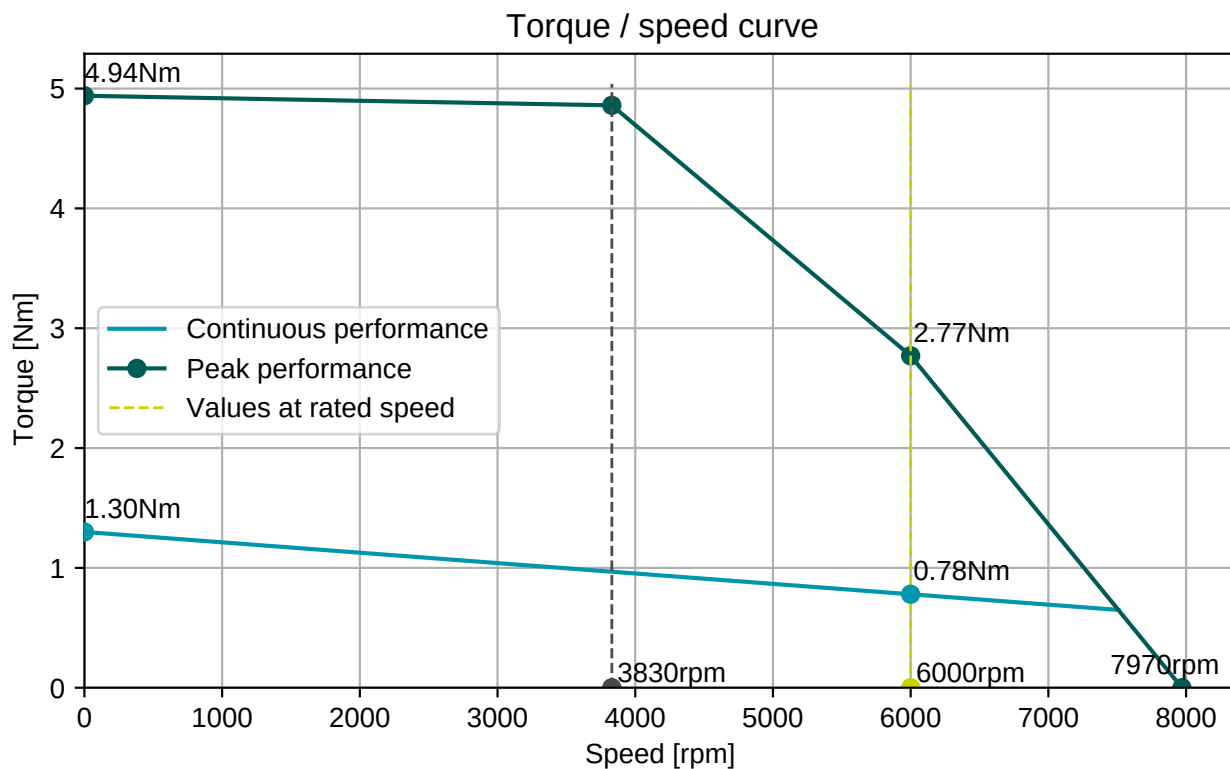
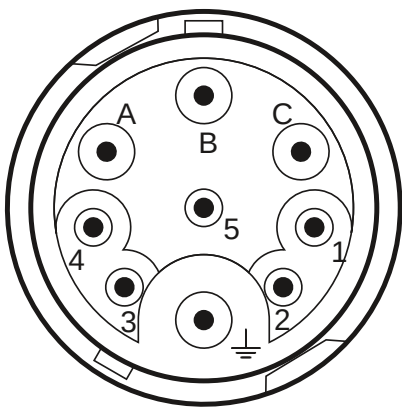


Engineering data (WIN 1439)		Mechanical data (setting 49)	
DC bus voltage	320 V DC	Max mechanical speed	12000 rpm
Nominal AC voltage	220 V AC (rms)	Mech. time constant	1.67 ms
Rated voltage	165 V AC (rms)	Thermal time constant	24 min
Rated power	490 W	Rotor inertia	0.5 kgcm ²
Rated speed	6000 rpm	Protection	IP64
Rated torque	0.78 Nm	Color	RAL 9005
Rated current	2.06 A (rms)	Cooling	Convection
Peak torque	4.94 Nm	Motor-only mass	2.1 kg
Peak current	13.5 A (rms)	Max. axial force 20kh	45 N
Stall torque	1.3 Nm	Max. radial force 20kh	237 N*
Stall current	2.86 A (rms)	Max. axial force 100kh	26 N
No load speed	7970 rpm	Max. radial force 100kh	139 N*
EMF constant ±10%	27.5 V AC (rms) / 1000rpm	* Defined for point of action at ½ output shaft length	
Theoretical torque constant ±10%	0.455 Nm / A (rms)		
Torque constant ±10% @ rated load	0.379 Nm / A (rms)		
Number of poles	10	Sensors	
Electrical time constant	1.34 ms	Temperature	PT1000 {PT1000}
Winding terminal resistance	3.99 Ω	Feedback	SKM36 (Hiperface) multi-turn, 128 sin/cos+12bits
Rotary field terminal inductance	5.35 mH	Brake	
Customs info		Braking torque	4.50 Nm
HS Code	85015100	Voltage	24 V DC
		Power @20°C	12.0 W
		Current @20°C	0.50 A
		Inertia	0.20 kgcm ²
		Mass	0.47 kg

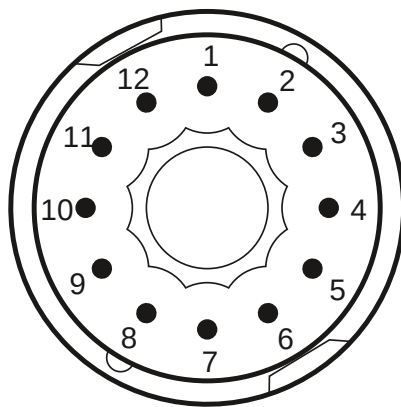


EGA101N00000001000
 2x M15, 9 and 12 poles rotary



Connector 1 (226)

A	U
B	V
C	W
PE	PE
1	Brake+
2	Brake-



Connector 2 (208)

1	Us
2	GND
3	+ COS
4	REFCOS
5	REFSIN
6	+ SIN
7	Therm+
8	Therm-
9	Data +
10	Data -

