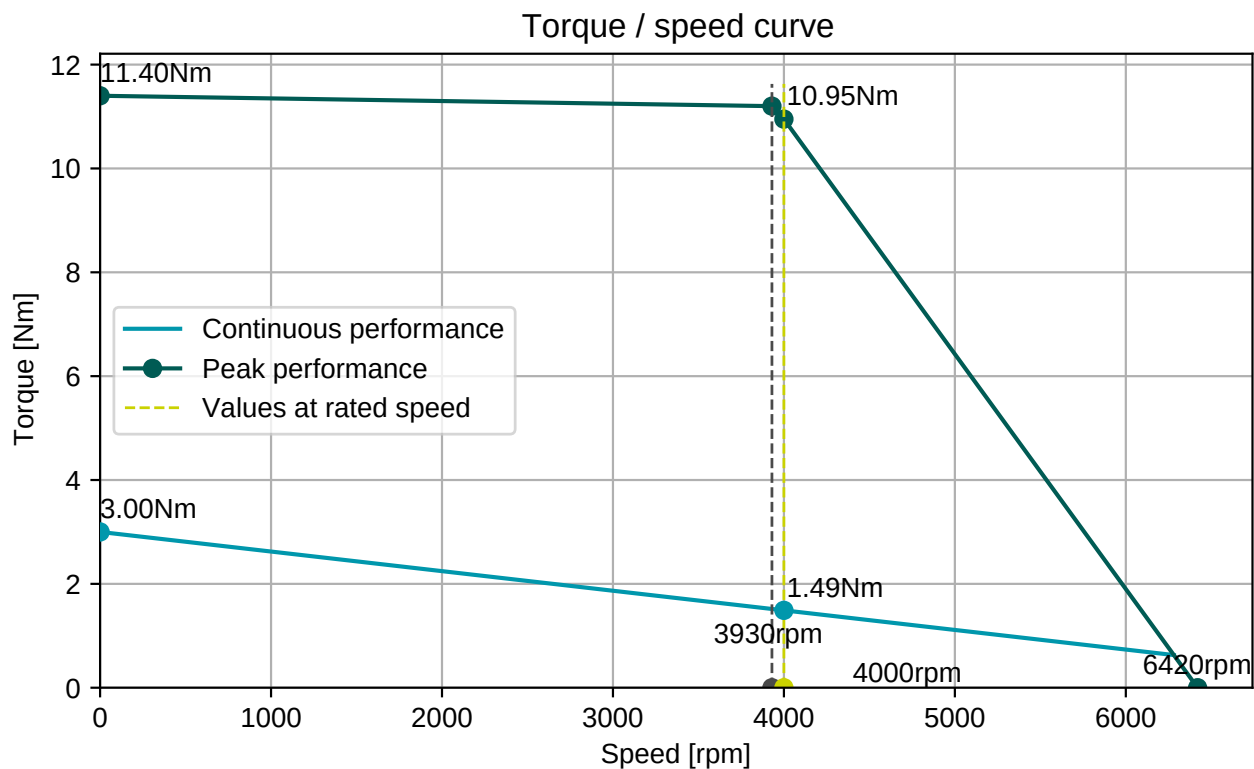
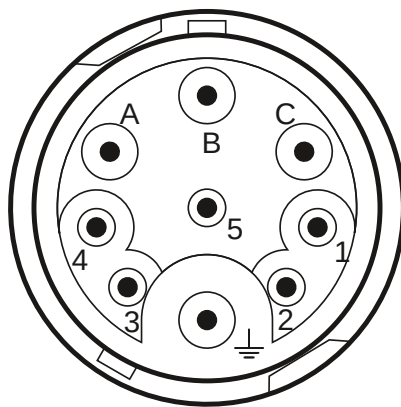


Engineering data (WIN 1532)		Mechanical data (setting 48)	
DC bus voltage	560 V DC	Max mechanical speed	12000 rpm
Nominal AC voltage	380 V AC (rms)	Mech. time constant	1.08 ms
Rated voltage	231 V AC (rms)	Thermal time constant	40 min
Rated power	624 W	Rotor inertia	1.2 kgcm ²
Rated speed	4000 rpm	Protection	IP64
Rated torque	1.49 Nm	Color	RAL 9005
Rated current	1.88 A (rms)	Cooling	Convection
Peak torque	11.4 Nm	Motor-only mass	3.3 kg
Peak current	13.2 A (rms)	Max. axial force 20kh	65 N
Stall torque	3 Nm	Max. radial force 20kh	342 N*
Stall current	3.07 A (rms)	Max. axial force 100kh	38 N
No load speed	6420 rpm	Max. radial force 100kh	200 N*
EMF constant ±10%	59 V AC (rms) / 1000rpm	* Defined for point of action at ½ output shaft length	
Theoretical torque constant ±10%	0.976 Nm / A (rms)		
Torque constant ±10% @ rated load	0.793 Nm / A (rms)		
Number of poles	10		
Electrical time constant	1.63 ms		
Winding terminal resistance	4.953 Ω		
Rotary field terminal inductance	8.06 mH		
Customs info		Sensors	
HS Code	85015100	Temperature	PT1000 {PT1000}
		Feedback	EKS36 (HDSL) single-turn, 18 bits, SIL2
		Brake	
		Braking torque	4.50 Nm
		Voltage	24 V DC
		Power @20°C	12.0 W
		Current @20°C	0.50 A
		Inertia	0.20 kgcm ²
		Mass	0.47 kg


EGA201N00000800000

M15, 9 poles, rotary


Connector 1 (304)

A	U
B	V
C	W
PE	PE
1	Brake+
2	Brake-
3	+Us/DSL+
4	GND/DSL-

