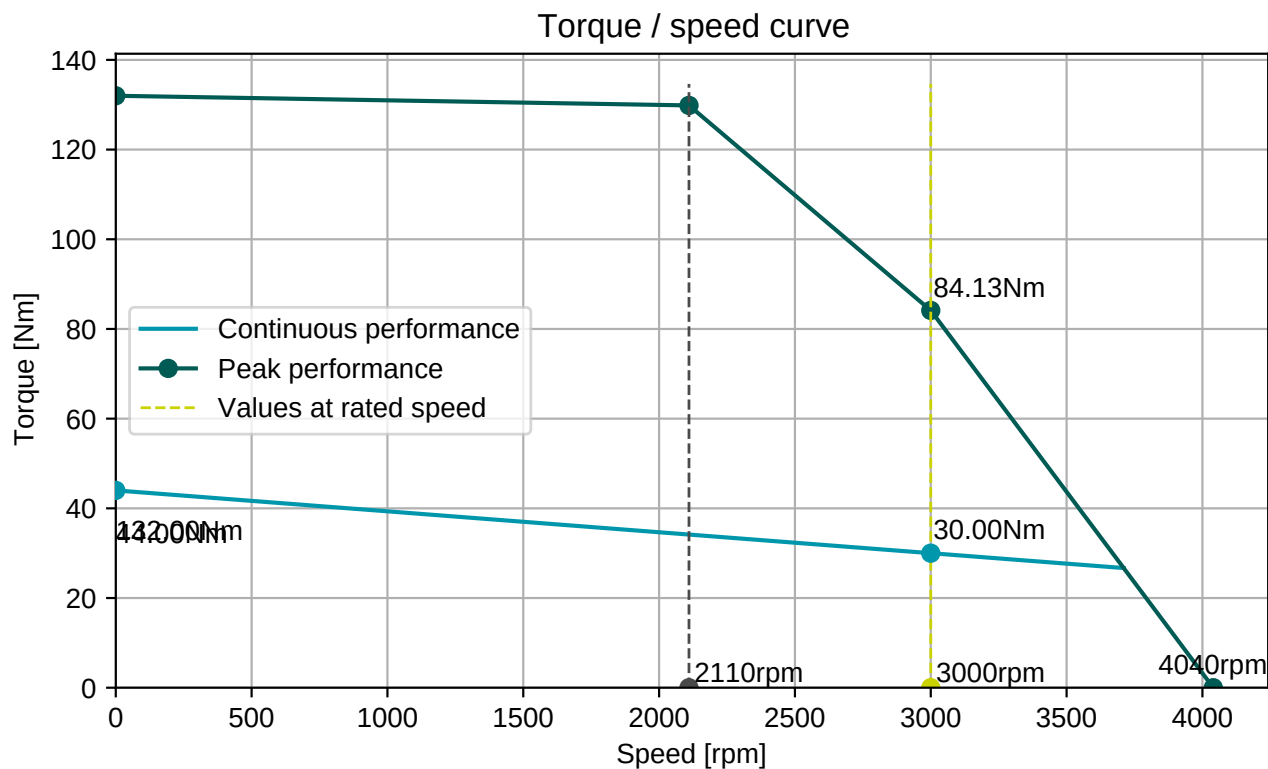


Engineering data (WIN 933)		Mechanical data (setting 48)	
DC bus voltage	560 V DC	Max mechanical speed	6000 rpm
Nominal AC voltage	380 V AC (rms)	Mech. time constant	0.64 ms
Rated voltage	267 V AC (rms)	Thermal time constant	62 min
Rated power	9.4 kW	Rotor inertia	47 kgcm ²
Rated speed	3000 rpm	Protection	IP64
Rated torque	30.00 Nm	Color	RAL 9005
Rated current	24.35 A (rms)	Cooling	Convection
Peak torque	132 Nm	Motor-only mass	25 kg
Peak current	101.6 A (rms)	Max. axial force 20kh	64 N
Stall torque	44 Nm	Max. radial force 20kh	335 N*
Stall current	28.3 A (rms)	Max. axial force 100kh	37 N
No load speed	4040 rpm	Max. radial force 100kh	196 N*
EMF constant ±10%	94 V AC (rms) / 1000rpm	* Defined for point of action at ½ output shaft length	
Theoretical torque constant ±10%	1.55 Nm / A (rms)		
Torque constant ±10% @ rated load	1.23 Nm / A (rms)		
Number of poles	10	Sensors	
Electrical time constant	14.74 ms	Temperature	PT1000 {PT1000}
Winding terminal resistance	0.19 Ω	Feedback	EKS36 (HDSL) single-turn, 18 bits, SIL2
Rotary field terminal inductance	2.8 mH	Brake	
Customs info		Braking torque	36.00 Nm
HS Code	85015230	Voltage	24 V DC
		Power @20°C	26.0 W
		Current @20°C	1.08 A
		Inertia	6.20 kgcm ²
		Mass	2.85 kg


BGC110N00001216000

M23, 8 poles, rotary


Connector 1 (283)

1	U
4	V
3	W
2	PE
A	Brake+
B	Brake-
C	GND/DSL-
D	+Us/DSL+

