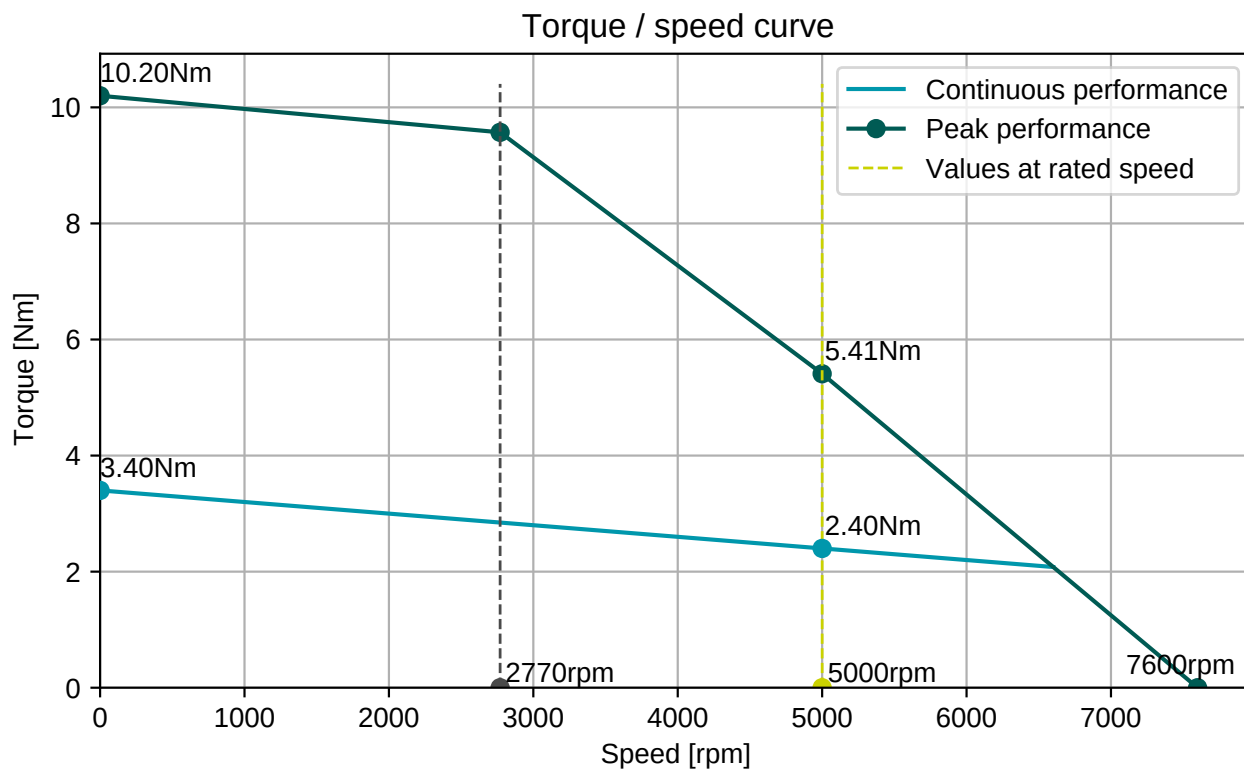
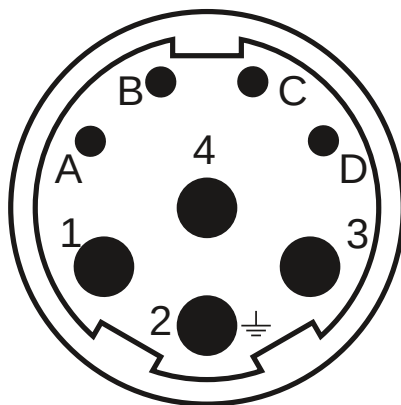


Engineering data (WIN 1156)		Mechanical data (setting 48)	
DC bus voltage	560 V DC	Max mechanical speed	9000 rpm
Nominal AC voltage	380 V AC (rms)	Mech. time constant	1.35 ms
Rated voltage	264 V AC (rms)	Thermal time constant	25 min
Rated power	1.3 kW	Rotor inertia	2.04 kgcm ²
Rated speed	5000 rpm	Protection	IP64
Rated torque	2.40 Nm	Color	RAL 9005
Rated current	4.22 A (rms)	Cooling	Convection
Peak torque	10.2 Nm	Motor-only mass	3.5 kg
Peak current	18.9 A (rms)	Max. axial force 20kh	68 N
Stall torque	3.4 Nm	Max. radial force 20kh	357 N*
Stall current	4.15 A (rms)	Max. axial force 100kh	40 N
No load speed	7600 rpm	Max. radial force 100kh	209 N*
EMF constant ±10%	49.5 V AC (rms) / 1000rpm	* Defined for point of action at ½ output shaft length	
Theoretical torque constant ±10%	0.82 Nm / A (rms)		
Torque constant ±10% @ rated load	0.57 Nm / A (rms)		
Number of poles	10	Sensors	
Electrical time constant	4.63 ms	Temperature	PT1000 {PT1000}
Winding terminal resistance	2.57 Ω	Feedback	EKM36 (HDSL) multi-turn, 18+12 bits, SIL2
Rotary field terminal inductance	11.9 mH	Brake	
Customs info		Braking torque	9.00 Nm
HS Code	85015220	Voltage	24 V DC
		Power @20°C	18.0 W
		Current @20°C	0.75 A
		Inertia	0.60 kgcm ²
		Mass	0.82 kg



BGC110N00001216000

M23, 8 poles, rotary



Connector 1 (283)

1	U
4	V
3	W
2	PE
A	Brake+
B	Brake-
C	GND/DSL-
D	+Us/DSL+

