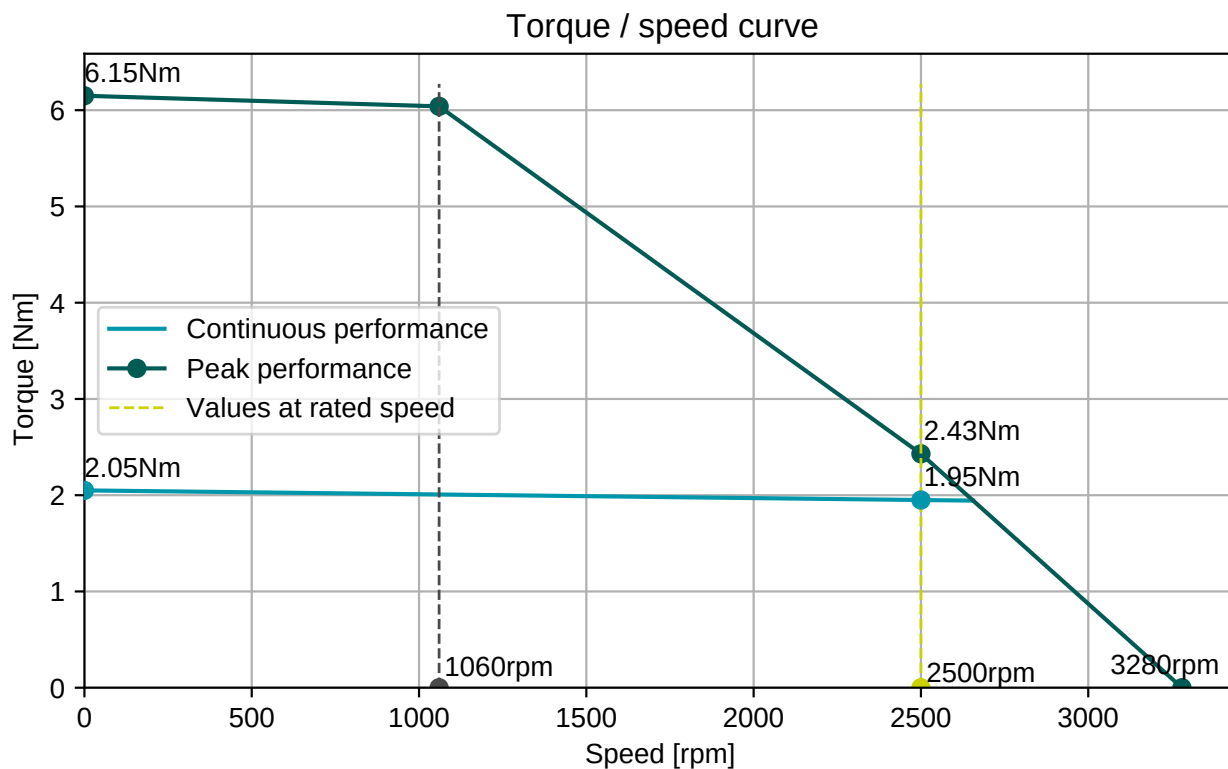


Engineering data (WIN 969)		Mechanical data (setting 48)	
DC bus voltage	48 V DC	Max mechanical speed	12000 rpm
Nominal AC voltage	33 V AC (rms)	Mech. time constant	0.94 ms
Rated voltage	30 V AC (rms)	Thermal time constant	23 min
Rated power	511 W	Rotor inertia	0.55 kgcm ²
Rated speed	2500 rpm	Protection	IP64
Rated torque	1.95 Nm	Color	RAL 9005
Rated current	13.67 A (rms)	Cooling	Convection
Peak torque	6.15 Nm	Motor-only mass	2 kg
Peak current	50.2 A (rms)	Max. axial force 20kh	68 N
Stall torque	2.05 Nm	Max. radial force 20kh	356 N*
Stall current	12.4 A (rms)	Max. axial force 100kh	40 N
No load speed	3280 rpm	Max. radial force 100kh	208 N*
EMF constant ±10%	10 V AC (rms) / 1000rpm	* Defined for point of action at ½ output shaft length	
Theoretical torque constant ±10%	0.17 Nm / A (rms)		
Torque constant ±10% @ rated load	0.14 Nm / A (rms)		
Number of poles	10	Sensors	
Electrical time constant	2.59 ms	Temperature	PT1000 {PT1000}
Winding terminal resistance	0.27 Ω	Feedback	EKS36 (HDSL) single-turn, 17 bits
Rotary field terminal inductance	0.7 mH	Brake	
Customs info		Braking torque	4.50 Nm
HS Code	85015100	Voltage	24 V DC
		Power @20°C	12.0 W
		Current @20°C	0.50 A
		Inertia	0.20 kgcm ²
		Mass	0.47 kg



BGC110N00001216000

M23, 8 poles, rotary



Connector 1 (283)

1	U
4	V
3	W
2	PE
A	Brake+
B	Brake-
C	GND/DSL-
D	+Us/DSL+

