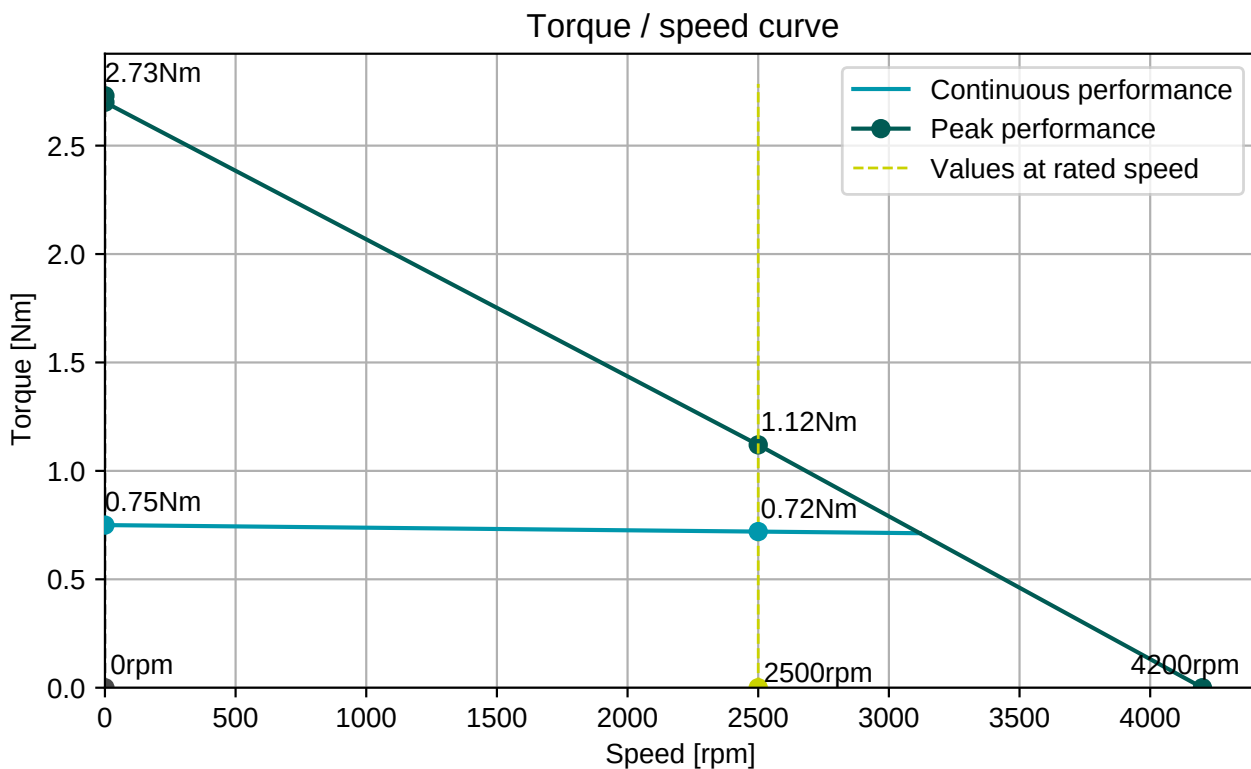
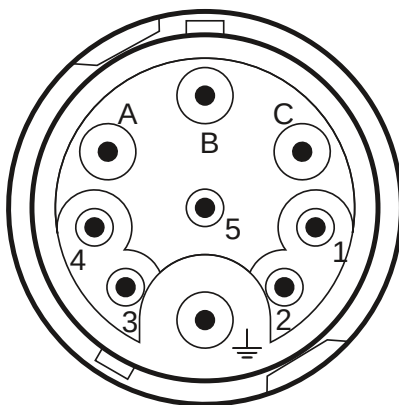


Engineering data (WIN 795)		Mechanical data (setting 48)	
DC bus voltage	36 V DC	Max mechanical speed	12000 rpm
Nominal AC voltage	25 V AC (rms)	Mech. time constant	1.15 ms
Rated voltage	21 V AC (rms)	Thermal time constant	12 min
Rated power	188 W	Rotor inertia	0.09 kgcm ²
Rated speed	2500 rpm	Protection	IP64
Rated torque	0.72 Nm	Color	RAL 9005
Rated current	7.8 A (rms)	Cooling	Convection
Peak torque	2.73 Nm	Motor-only mass	1.35 kg
Peak current	31.2 A (rms)	Max. axial force 20kh	52 N
Stall torque	0.75 Nm	Max. radial force 20kh	276 N*
Stall current	7.7 A (rms)	Max. axial force 100kh	31 N
No load speed	4200 rpm	Max. radial force 100kh	161 N*
EMF constant ±10%	5.9 V AC (rms) / 1000rpm	<i>* Defined for point of action at ½ output shaft length</i>	
Theoretical torque constant ±10%	0.1 Nm / A (rms)		
Torque constant ±10% @ rated load	0.1 Nm / A (rms)		
Number of poles	6	Sensors	
Electrical time constant	1.27 ms	Temperature	PT1000 {PT1000}
Winding terminal resistance	0.7 Ω	Feedback	EKM36 (HDSL) multi-turn, 17 + 12 bits
Rotary field terminal inductance	0.89 mH	Brake	
Customs info		Braking torque	2.00 Nm
HS Code	85015100	Voltage	24 V DC
		Power @20°C	11.0 W
		Current @20°C	0.46 A
		Inertia	0.08 kgcm ²
		Mass	0.20 kg


EGA201N00000800000

M15, 9 poles, rotary


Connector 1 (304)

A	U
B	V
C	W
PE	PE
1	Brake+
2	Brake-
3	+Us/DSL+
4	GND/DSL-

