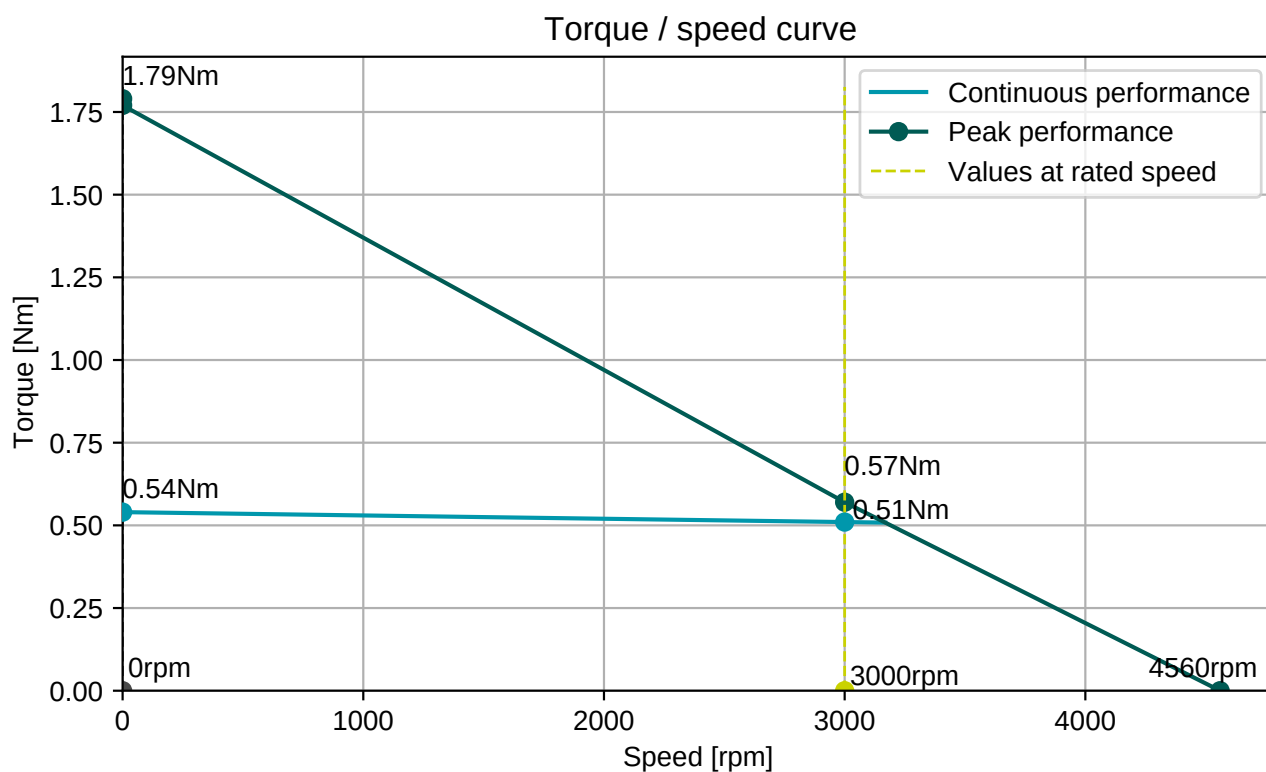
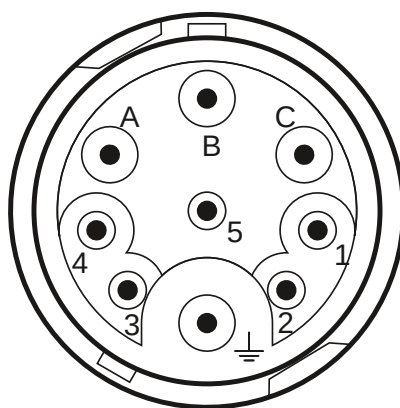


Engineering data (WIN 1486)		Mechanical data (setting 48)	
DC bus voltage	24 V DC	Max mechanical speed	12000 rpm
Nominal AC voltage	17 V AC (rms)	Mech. time constant	1.46 ms
Rated voltage	16 V AC (rms)	Thermal time constant	12 min
Rated power	160 W	Rotor inertia	0.07 kgcm ²
Rated speed	3000 rpm	Protection	IP64
Rated torque	0.51 Nm	Color	RAL 9005
Rated current	9.01 A (rms)	Cooling	Convection
Peak torque	1.79 Nm	Motor-only mass	0.9 kg
Peak current	32.1 A (rms)	Max. axial force 20kh	48 N
Stall torque	0.54 Nm	Max. radial force 20kh	254 N*
Stall current	8.9 A (rms)	Max. axial force 100kh	28 N
No load speed	4560 rpm	Max. radial force 100kh	149 N*
EMF constant ±10%	3.65 V AC (rms) / 1000rpm	* Defined for point of action at ½ output shaft length	
Theoretical torque constant ±10%	0.06 Nm / A (rms)		
Torque constant ±10% @ rated load	0.06 Nm / A (rms)		
Number of poles	6	Sensors	
Electrical time constant	1.26 ms	Temperature	PT1000 {PT1000}
Winding terminal resistance	0.438 Ω	Feedback	EES37 (HDSL) single-turn, 17 bits
Rotary field terminal inductance	0.55 mH	Brake	
Customs info		Braking torque	2.00 Nm
HS Code	85015100	Voltage	24 V DC
		Power @20°C	11.0 W
		Current @20°C	0.46 A
		Inertia	0.08 kgcm ²
		Mass	0.20 kg


EGA201N00000800000

M15, 9 poles, rotary


Connector 1 (304)

A	U
B	V
C	W
PE	PE
1	Brake+
2	Brake-
3	+Us/DSL+
4	GND/DSL-

