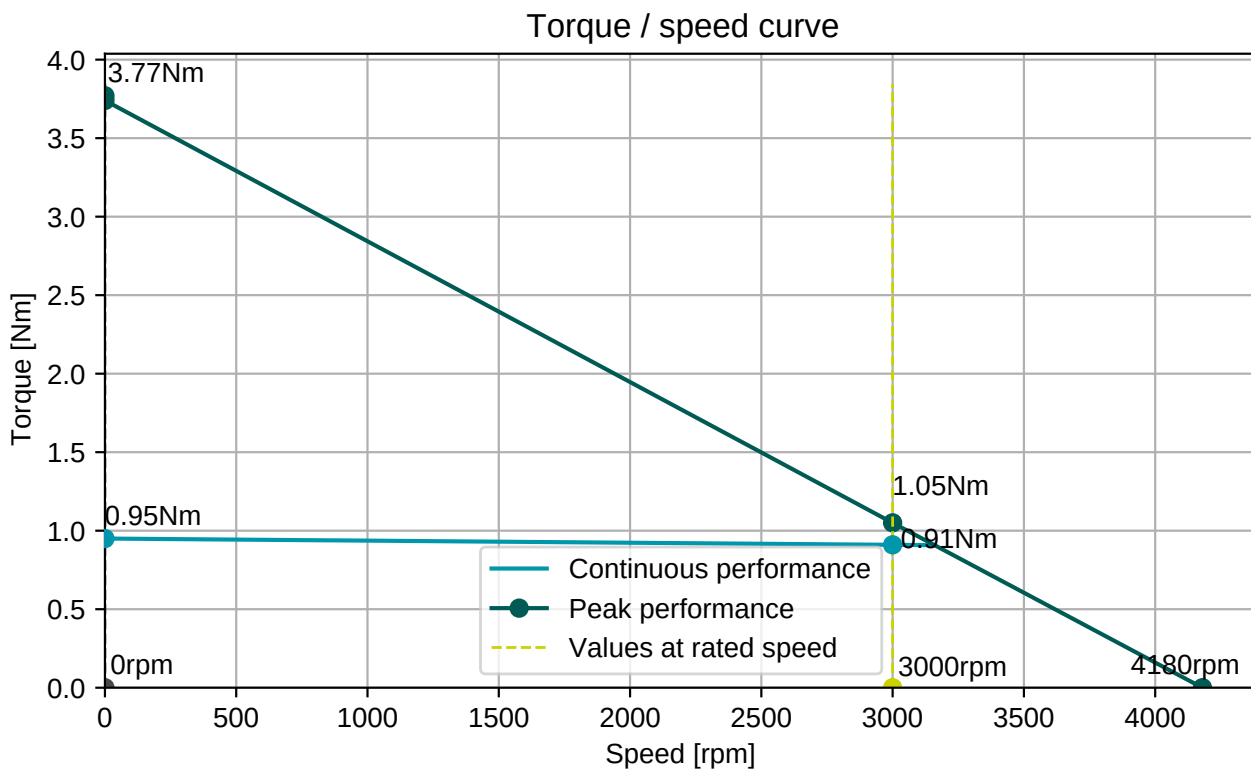


Engineering data (WIN 1035)		Mechanical data (setting 48)	
DC bus voltage	48 V DC	Max mechanical speed	12000 rpm
Nominal AC voltage	33 V AC (rms)	Mech. time constant	1.00 ms
Rated voltage	32 V AC (rms)	Thermal time constant	18 min
Rated power	286 W	Rotor inertia	0.11 kgcm ²
Rated speed	3000 rpm	Protection	IP64
Rated torque	0.91 Nm	Color	RAL 9005
Rated current	7.31 A (rms)	Cooling	Convection
Peak torque	3.77 Nm	Motor-only mass	1.7 kg
Peak current	33.4 A (rms)	Max. axial force 20kh	50 N
Stall torque	0.95 Nm	Max. radial force 20kh	264 N*
Stall current	7.3 A (rms)	Max. axial force 100kh	29 N
No load speed	4180 rpm	Max. radial force 100kh	154 N*
EMF constant ±10%	7.8 V AC (rms) / 1000rpm	* Defined for point of action at ½ output shaft length	
Theoretical torque constant ±10%	0.13 Nm / A (rms)		
Torque constant ±10% @ rated load	0.12 Nm / A (rms)		
Number of poles	6	Sensors	
Electrical time constant	1.36 ms	Temperature	PT1000 {PT1000}
Winding terminal resistance	0.87 Ω	Feedback	EKM36 (HDSL) multi-turn, 18+12 bits, SIL2
Rotary field terminal inductance	1.18 mH	Brake	
Customs info		Braking torque	2.00 Nm
HS Code	85015100	Voltage	24 V DC
		Power @20°C	11.0 W
		Current @20°C	0.46 A
		Inertia	0.08 kgcm ²
		Mass	0.20 kg


BGC110N00001216000

M23, 8 poles, rotary


Connector 1 (283)

1	U
4	V
3	W
2	PE
A	Brake+
B	Brake-
C	GND/DSL-
D	+Us/DSL+

